Radial Fractional–Order Dispersion Through Fractured Rock

David Benson
Desert Research Institute, Reno, Nevada, USA

Charles Tadjeran
University of Nevada, Reno, USA

Mark M. Meerschaert
University of Nevada, Reno, USA

Irene Farnham
Stoller Navarro Joint Venture, Las Vegas, Nevada, USA

Greg Pohll
Desert Research Institute, Reno, Nevada, USA

Abstract. A solute transport equation with a fractional–order dispersion term is a model of solute movement in aquifers with very wide distributions of velocity. The equation is typically formulated in Cartesian coordinates with constant coefficients. In situations where wells may act as either sources or sinks in these models, a radial coordinate system provides a more natural framework for deriving the resulting differential equations and the associated initial and boundary conditions. We provide the fractional radial flow advection–dispersion equation with non–constant coefficients and develop a stable numerical solution using finite differences. The hallmark of a spatially fractional–order dispersion term is the rapid transport of the leading edge of a plume compared to the classical Fickian model. The numerical solution of the fractional radial transport equation is able to reproduce the early breakthrough of bromide observed in a radial tracer test conducted in a fractured granite aquifer. The early breakthrough of bromide is under–predicted by the classical radial transport model. Another conservative, yet non–naturally occurring solute (pentafluorobenzoate), also shows early breakthrough but does not conclusively support the bromide model due to poor detection at very low concentrations. The solution method includes, through a procedure called subordination, the effects of solute partitioning to immobile water.

1. Introduction

Due to time constraints, tracer tests are often conducted under forced gradients. In particular, the radial flow regime induced by a pumping well is often used to estimate the parameters needed for prediction of long–term transport under natural gradients. The effective porosity (for velocity) and dispersivity (for the dispersion tensor) are two parameters that are used in a Fickian, second–order advection–dispersion governing equation of motion. The effect of the radial geometry, aquifer heterogeneity, and test size on the applicability and/or scale–dependency of the estimates has been demonstrated by Chao et al. [2000] and Reimus [2003]. An alternative to a scale–dependent dispersion coefficient in a Fickian model is a fractional–order dispersion term, which accounts for a non–Fickian plume scaling rate and a heavy (power law) leading edge of the plume moving under natural gradient conditions [Benson et al., 2001]. The fractional–order dispersion derivative is a consequence of a highly heterogeneous, power–law distribution of water velocities and long–range correlation or preferential flow [Herrick et al., 2003; Benson et al., 2000a; Cushman and Ginn, 2002]. In this study, a power–law (fractal) distribution refers to the asymptotic relation $P(X > x) \sim x^{-b}$ for positive $b$ [Mandelbrot, 1982]. A power–law distribution, with $b < 2$, of solute particle travel distance over some period of time induces a fractional dispersion derivative, in tandem with linear drift (mean advection), in the governing equation of motion [Saichev and Zaslavsky, 1997; Chaves, 1997; Benson, 1998].

While this study will focus on early arrivals to an extraction well, no analysis of breakthrough curves (BTC) can ignore the effects of solute retention and late–time tailing. Here we provide a brief review. Two primary models exist that represent end members of possible behavior. The mobile/immobile (MIM) model assumes that solute particles spend random amounts of time in an immobile phase. Solute that spends power–law–distributed random amounts of time (with $b < 2$) in an immobile phase induces a fractional–order time derivative in the governing equation [Schumer, 2002; Dents and Berkowitz, 2003; Schumer et al., 2003; Baenner et al., 2004]. In the fractal MIM model, the two vastly different extreme behaviors that generate fractional space and time derivatives (rapid transport and long–term immobilization, respectively) are considered independent, or uncoupled [Haggerty et al., 2000]. The uncoupling of immobilization time and the subsequent velocity allows simple computation of the breakthrough curves through a process called subordination [Feller, 1971; Schumer et al., 2003]. This process is...
also equivalent to uncoupled continuous time random walk (CTRW) models [Montroll and Weiss, 1965; Shlesinger et al., 1982; Grubert, 2001; Berkowitz et al., 2002; Dents and Berkowitz, 2003; Bromly et al., 2004; Cortis et al., 2004]. For solute transport, subordination replaces the deterministic clock time that a particle spends undergoing a motion process with a random “operational time.”

On the other hand, Becker and Shapiro [2003] describe numerous BTC using a model in which tracer mass in any streamtube is fixed and proportional to the water flux in the streamtube. The retention is not due to random trapping in immobile zones. Instead, it is due to the presence of streamtubes with arbitrarily slow advection, so the retention is directly coupled to velocity. Certain types of coupled processes, along with the uncoupled process, generate unique fractional-order governing equations with some similar properties [Meerschaert et al., 2002; Schmidt et al., 1972; Haldeman et al., 1985, 1988, 1990; Bouchaud et al., 1999] and can be modeled using fractional calculus (representing deviations from the common drift velocity). The classical Fickian model uses mean advective flux defined by

\[ q_1(r,t) = v(r) c, \]

and Fick’s Law for dispersive flux based on empirical observations, defined by

\[ q_2(r,t) = -d(r) \frac{\partial c}{\partial r}, \]

where \( c = c(r,t) \) is the concentration of the solute (with radial symmetry), and \( f(r,t) \) is a forcing function that may be used to model the injection or extraction of solute as a function of space and time. The total flux \( q(r,t) = q_1(r,t) + q_2(r,t) \), where \( q_1(r,t) \) is the common drift (mean advecive) flux, and \( q_2(r,t) \) is the dispersive flux.

\[ \frac{\partial c}{\partial t} = -\frac{1}{r} \frac{\partial}{\partial r} \left[ r q(r,t) \right] + f(r,t) \]

In Becker and Shapiro’s [2003] model, all solutes experience the same non-zero velocity distribution and travel identically. It is highly likely that both the coupled and uncoupled mechanisms contribute to the overall retention in any single fractured system. The relative degree of each mechanism is best discerned using the extremely late breakthrough, since these solute particles have experienced either diffusive-limited transport or very slow co-advection. Different tests, using multiple tracers with significantly different diffusion coefficients, have been analyzed assuming one or the other model with good results [Becker and Shapiro, 2003; Haggerty et al., 2000; Reimus et al., 2003].

To distinguish between the space and time operations, we call these effects fractional dispersion and fractal retention, respectively. In subsurface hydrology at the field scale, the fractional dispersion approach has only been used to model natural gradient tests in saturated, granular, aquifer material [Benson et al., 2000b, 2001]. A recent forced-gradient test conducted in a fractured granite aquifer [Reimus et al., 2003] shows some of the characteristics of anomalous transport. The conservative bromide tracer arrives at the extraction well far in advance of the classical (Fickian) model. We theorize that flow in the fractures or fracture network is highly heterogeneous [see, e.g., Tsang and Tsang, 1987; Moreno et al., 1985, 1988, 1990; Haldeman et al., 1991; Thompson, 1991; Johns and Roberts, 1991; Brown, 1989; Muratova et al., 1995; Keller et al., 1999] and can be modeled with the fractional dispersion approach. Furthermore, the test shows the fingerprint of long-term solute retention, with incomplete mass recovery and anomalous late-time breakthrough. Reimus et al. [2003] use a classical advection-dispersion model of transport in the fractures, coupled to an immobile phase in identically-sized matrix blocks to fit the data. We formulate and solve the radial solute transport problem for a fractional-order dispersion derivative in order to better fit the early-time BTC, and include the effects of communication with an immobile phase with long-term waiting times in a manner similar to Haggerty et al. [2000], Reimus et al. [2003], Dents and Berkowitz [2003] and Schumacher et al. [2003]. An analysis of Becker and Shapiro’s [2003] coupled retention is beyond the scope of this study, and as we will show, not possible with the incomplete BTC tail data.

If the time that a solute particle spends in a volume of immobile water (whether in–fracture or extra–fracture “matrix” water) is independent of the speed at which the particle travels when released back in the mobile fracture water, then the breakthrough curve can be solved using two independent models. The first is the transport in the mobile phase alone. This solution is then subordinated according to the distribution of random waiting times in an immobile phase [Schumer et al., 2003; Scalas et al., 2004]. We assume this independence (as do all MIM models) so that we can solve the spatially fractional problem in radial coordinates and simply transform the solution to include solute retention.

Before deriving the fractional–order, radially convergent, mobile–phase transport equation, we begin with conservation of mass of a purely mobile solute in cylindrical coordinates [Hoopes and Harleman, 1967]:

\[ \frac{\partial c}{\partial t} = -\frac{1}{r} \frac{\partial}{\partial r} \left[ r q(r,t) \right] + f(r,t) \]

where \( c = c(r,t) \) is the concentration of the solute (with radial symmetry), and \( f(r,t) \) is a forcing function that may be used to model the injection or extraction of solute as a function of space and time. The total flux \( q(r,t) = q_1(r,t) + q_2(r,t) \), where \( q_1(r,t) \) is the common drift (mean advective) flux, and \( q_2(r,t) \) is the dispersive flux (representing deviations from the common drift velocity). The classical Fickian model uses mean advective flux defined by

\[ q_1(r,t) = v(r) c, \]

and Fick’s Law for dispersive flux based on empirical observations, defined by

\[ q_2(r,t) = -d(r) \frac{\partial c}{\partial r}, \]

where \( v(r) \) is the common drift velocity, and \( d(r) \) is the dispersion coefficient, both of which are functions of the radius.

In a uniform porous medium of thickness \( b \) with porosity \( \theta \), with a radial flow toward the extraction well pumping at rate \( Q \), the advective velocity is given by

\[ v(r) = \frac{Q}{2\pi rb \theta} = \frac{\kappa_v}{r} \]

for some constant \( \kappa_v = Q/2\pi rb \theta \). Moreover, a working assumption typically is made [Bear, 1972] or measured [e.g., Hoopes and Harleman, 1967] that the hydrodynamic dispersion coefficient at any point is proportional to the velocity.

Therefore, we may write:

\[ d(r) = \frac{a\kappa_v}{r} \]

for some constant dispersive coefficient \( a \). If these expressions for \( v(r) \) and \( d(r) \) are substituted in (1), then after some simple manipulations we obtain

\[ \frac{\partial c}{\partial t} = -\frac{\kappa_v}{r} \frac{\partial c}{\partial r} + \frac{a\kappa_v}{r} \frac{\partial^2 c}{\partial r^2} + f(r,t), \]

subject to the appropriate initial and boundary conditions.

2. Radial Fractional Advection–Dispersion Equation

Early arrivals of solute at an extraction well may not be predicted by the classical Fickian model. In natural gradient tests, a fractional–order Fick’s Law is a model of anomalously rapid transport [Benson et al., 2001; Paradisi et al.,]
of the dispersive flux is substituted into (1), we get:

\[ q_2(r, t) = -d(r) \frac{\partial^{\alpha-1} c(r, t)}{\partial r^{\alpha-1}}. \]

where the fractional derivative on the right–hand side is defined by the domain of the problem (Appendix). Since our radial flow problem exists within a finite domain, we use the Riemann–Liouville (with the corresponding Grünwald formulation) fractional derivative [Oldham and Spanier, 1974; Miller and Ross, 1993].

The fractional term directly models anomalous dispersion due to extreme velocity contrasts. In the case of flow within fractures, the dominant mechanism is thought to be channelization of the flow into distinct preferential pathways [Moreno et al., 1985; Tsang and Tsang, 1987; Brown, 1989]. Under this model, the velocity contrasts also lead to growth rate of a plume under natural gradient conditions faster than the Fickian rate of \( t^{1/2} \) [Benson et al., 2000b]. When this form of the dispersive flux is substituted into (1), we get:

\[ \frac{\partial c}{\partial t} = -\alpha \frac{\kappa_c}{r} \frac{\partial c}{\partial r} + \alpha \kappa_a \frac{\partial^{\alpha} c}{\partial r^{\alpha}} + f(r, t). \tag{3} \]

The forcing function can model the injection of the solute at the injection well. The units of \( a \) are \( L^{\alpha-1} \) so that \( d(r) = \alpha \kappa_a / r \) has dimension \( L^{\alpha}/T \). A mass–conservative and nonnegative solution requires that \( 0 < \alpha \leq 2 \). For convenience we assume \( v(r) \geq 0 \) and \( d(r) \geq 0 \) so that the flow is from left to right in the finite domain between left and right (outer and inner) boundaries \( R_0 < r < R_1 \). This induces a somewhat unorthodox coordinate system with \( r \leq 0 \) that works naturally with the directional fractional derivative (Appendix). In general we may assume an initial condition \( c(r, t = 0) = F(r) \) for \( R_0 < r < R_1 \) and a natural set of boundary conditions for this problem: \( c(r = R_0, t) = 0 \) for all \( t \geq 0 \) and \( \partial c(r = R_1, t) / \partial r = 0 \) for all \( t \geq 0 \) (Fig. 1). Physically, the boundary conditions mean that no tracer leaks past the outer boundary, and that the tracer moves by advection through the inner boundary (and into the extraction well). No solute may diffuse or disperse out of the extraction well into the formation. Since our problem models the effluent from an extraction well, \( c(r, t) \) represents the flux–averaged concentration; however, since \( \partial c(r = R_1, t) / \partial r = 0 \), the resident and flux concentrations are equivalent at the extraction well [Moench, 1989].

The fractional derivative formulation is a generalization of the standard model, and provides a fractional-order parameter that can be estimated to properly model the arrival of the solute at the extraction well. See Benson et al. [2001] and Herrick et al. [2003] for some practical methods of estimating the order \( \alpha \) of the fractional derivative from hydraulic conductivity data. Analytic solutions to the fractional PDE (3) are elusive, but do exist for some analytic expressions of \( v, d, \) and \( f \). In general, the resulting spatially fractional advection dispersion equation is solved by numerical methods and can be validated against the few analytic solutions [Meerschaert and Tadjeran, 2003].

An implicit Euler method, based on a modified Grünwald approximation to the fractional derivative, (or a similarly defined Crank–Nicholson finite difference method) is a consistent and unconditionally stable numerical solution [Meerschaert and Tadjeran, 2003]. We use this method to provide convergent numerical solutions for the fractional radial flow equation with variable velocity and dispersion coefficients (Appendix).
where $\beta[T^{-1}]$ is a fractal capacity coefficient, $0 < \gamma \leq 1$, and the Caputo fractional time derivative is defined by its Laplace transform $s^{\gamma-1}(s\hat{c}(r,s) - c(r,t=0))$. The solution may be gained by first solving the mobile–only solution $\partial m/\partial t = Am + F(r)\delta(t)$ and subordinating the result via the integration:

$$c(r,t) = \int_0^t m(r,u)g_r\left(\frac{t-u}{(\beta u)^{1/\gamma}}\right)(\beta u)^{-1/\gamma}du,$$

where the function $g_r(t)$ with Laplace transform $\hat{g}(s) = \exp(-s^\gamma)$ is the probability density function of the limit of an appropriately scaled sum of heavy–tailed waiting times [Schumer et al., 2003]. A subordination integral [Feller, 1971] accounts for the fact that a particle participates in the equation of motion (1) for only a portion of the “clock” time. The long–time tail of $g_r(t)$ decays like $t^{-1-\gamma}$, so this formulation includes the diffusion of solutes into infinite matrix blocks with a return time density with $\gamma = 1/2$ [e.g., Tsang, 1995; Haggerty et al., 2000]. Long–term tests in fractured [Haggerty et al., 2000] and granular [Schumer et al., 2003] aquifers indicate different values of $\gamma$ between zero and unity.

### 4. Model Properties

The novel elements of the model (4), when a radial fractional dispersion model is used for the purely mobile phase, are the orders of the dispersion derivative ($\alpha$) and the time derivative ($\gamma$). Using the same boundary value problem defined by the Shoal tracer test (Fig. 1, described in Sec. 5) and holding all other parameters constant ($\kappa_0 = \alpha = 1$), we investigate the effect of varying both of these derivatives. When $\gamma = 1$, the term $(1 + \beta)$ is identical to the classical retardation coefficient, so we first set $\beta = 0$ and vary $\alpha$ over the set $[2.0, 1.8, 1.6, 1.4]$. The most notable effect of increased $\alpha$ is the early arrival of the leading edge of the plume (Fig. 2). This is accompanied by an overall increase in the width of the breakthrough curve.

To illustrate the effect of the fractional time derivative, we hold $\alpha = 2$ and $\beta = 0.005$ and vary $\gamma$ over the set $[0.3, 0.4, 0.5, 0.6, 0.7, 1.0]$. When $0 < \gamma < 1$ the late–time breakthrough curve (Fig. 3a) decays like $c(r,t) \sim t^{-1-\gamma}$ [Haggerty et al., 2000; Schumer et al., 2003; Dentz and Berkowitz, 2003]. Lower values of $\gamma$, with the same capacity coefficient $\beta$, have a clearly reduced peak concentration and somewhat delayed peak arrival time, both due to the increased proportion of long times in an immobile phase (Fig. 3b). The effects of the fractional space and time derivatives are, for the most part, independent. Each non-integer order derivative adds a “wing” to the Fickian BTC.

### 5. Application

In a recent field study conducted in a fractured granite aquifer [Reimus et al., 2003], a predominantly radial flow regime was induced by pumping an extraction well at a rate of $Q = 16.3$ m$^3$/day and reinjecting approximately 10% of the water into the eventual tracer injection well. Upon reaching a relatively steady–state, a mixture of two conservative solutes and one sorbing solute were introduced at the injection well for a period of 3.54 days. Within the mixture, 20.81 kg of bromide, at an average concentration of 3.77 kg/m$^3$, and 2.19 kg of pentfluorobenzoate (PFBA) at an average concentration of 0.397 kg/m$^3$ were included. Samples from the extraction well were separately analyzed for both of these relatively conservative solutes using ion chromatography for bromide and high–pressure liquid chromatography for PFBA. Over the course of the test, the extraction rate declined steadily, giving an average extraction rate of approximately $Q = 12.4$ m$^3$/day. The distance from the injection well to the extraction well is 30 m, and the radius of the extraction well is 0.127 m. The extraction well screened interval is 35 m, so $r(r) = Q/(2\pi\theta r) = 0.0564/(r\theta)$ m$^2$/day, and $d(r) = \alpha n(r)$. This gives two parameters that describe the velocity and dispersion: the mobile, or effective, porosity $\theta$ and the dispersivity $a$. The remaining fitting parameters are the fractional dispersion order $\alpha$, describing anomalously early arrivals, and the order and capacity coefficient of the heavy–tailed waiting times $\gamma$ and $\beta$. For diffusion from a single smooth fracture of constant aperture $b$ into infinite immobile slabs, $\gamma = 1/2$ and $\beta = \phi\sqrt{D_m}/b$, where $\phi$ is the matrix porosity, and $D_m$ is the diffusion coefficient in the matrix [Haggerty et al., 2000; Reimus et al., 2003].

In the numerical solution (Figure 1), we use outer and inner boundaries to the radial domain of $R_O = -60.127$ m and $R_I = -0.127$ m. The injection well is at $r_L = -30.127$ m, the extraction well is centered at $r = 0$, with its wall at $r = R_I = -0.127$ m. Both are assumed to have negligible well–bore mixing. The outer boundary is set to be upstream and sufficiently far from the injection well so that no measurable bromide concentration reaches the outer boundary during the time of interest. Therefore, we may assume $c(r = R_O, t) = 0$, and $\partial c(r = R_I, t)/\partial r = 0$. The

---

**Figure 3.** Log–log and linear plots of normalized concentration ($c(R_I,t)Q/M$) at a central well for several values of the immobile parameter $\gamma$. Purely mobile solute undergoing Fickian dispersion is shown by the curve $\gamma = 1.0$. 

---

*Note: The image contains plots showing the concentration over time for different values of $\gamma$. The plots are labeled with different $\gamma$ values and show the decrease in concentration with increasing $\gamma$. The plots are presented in both log–log and linear formats for comparison.*
injection of solutes occurred over a short enough time period, followed by flushing, that the forcing function is approximated by a Dirac delta function in space and time
\[ f(r, t) = M \delta(r - r_L) \delta(t)/2\pi r_L b \theta, \]
where \( M \) is the injected mass (Figure 1).

A graph of bromide concentration at the extraction well as a function of time, along with the results of numerical estimates using the subordinated implicit Euler method are shown in Figure 4. All concentrations are normalized by the factor \( Q/M \) so that complete recovery of the solute would integrate to unity. We find that the hydraulic parameters \( \theta = 0.015, \sigma = 2 \text{ m}^2 \text{d}^{-1}, \alpha = 1.95 \) and temporal subordination parameters \( \beta = 0.116 \text{ day}^{-1/2} \) provide a fit to most of the data. In agreement with Reimus et al.’s [2003] analysis of the data, we find that the problem is highly non-unique: since the dispersivity and retention within an immobile matrix both serve to spread the solute arrival, a large set of parameters fit the data equally well. Unfortunately, the test was stopped before sufficient data could uniquely resolve the late-time tail parameters \( \gamma \) and \( \beta \) (compare Fig. 3a and Fig. 4a). However we wish to stress that a space-fractional derivative of order \( \alpha < 2 \) seems necessary to capture the early-time arrivals, and a time-fractional derivative of order \( \gamma < 1 \) was required to fit the late arrivals. The classical radial flow model (Fig. 4a) greatly under-estimates the early arrival of bromide. For reference, the parameters in the classical \( \alpha = 2 \) model shown in Figure 4 are \( \theta = 0.026, \sigma = 5 \text{ m}, \gamma = 1/2, \) and \( \beta = 0.065 \text{ day}^{-1/2} \), although a range of parameters fit equally well.

The lack of complete tail data also does not allow us to differentiate between tailing models based on diffusion into immobile water versus slow advection. For these reasons we choose \( \gamma = 1/2 \), which is the standard solution for diffusion into infinite immobile slabs. The \( \gamma = 1/2 \) solution is the genesis for the “\(-3/2\) law” describing the slope of the late-time BTC on a log-log plot [see e.g., Tsang, 1995; Hagerty et al., 2000]. The fractional radial flow model captures the early breakthrough of bromide at the extraction well, as well as the late-time tailing. The (normalized) PFBA breakthrough is very similar to the that of bromide, suggesting either that the slow pathways are not primarily due to diffusion into stagnant zones [e.g., Becker and Shapiro, 2003] or that a significant portion of the injected mass is not within the capture zone of the extraction well [Reimus et al., 2003].

PFBA samples collected prior to 37 days were reported as containing less than the detection limit. To investigate whether early breakthrough of bromide is indeed anomalous, we inspected the chromatograms provided by the Harry Reid Center (Las Vegas, NV) for the PFBA analysis. The chromatograms for early samples collected from 20 to 37 days show peaks at retention times similar to PFBA, though the peaks are not always statistically significantly greater than background noise. We used the PFBA peak areas listed on the chromatograms and show the mean over multiple sample injections plus or minus one standard deviation (Fig. 4a). While the PFBA data show wide scatter and hover close to the statistically significant detection limit, they do tend to show anomalously early arrival relative to the fickian model (Fig. 4a). However, due to the poor reliability of the PFBA data, we do not consider this a confirmation or a repudiation of the fractional transport model at this site. An artificial tracer with extremely low detection limits (e.g., DNA strands, Sabir et al. [1999]) could be useful in the accurate determination of fast pathways modelled by a fractional dispersion term.

The fractal MIM model with \( \gamma = 1/2 \) reproduces the recovery of roughly 20% of the bromide mass by the end of the test, and predicts that only about 80% of the mass would be recovered if the test were run forever, due to the irreversible loss of mass to an immobile phase. Furthermore, our values of \( \beta = 0.065 \text{ d}^{-1/2} \) and \( 0.116 \text{ d}^{-1/2} \) for the classical and fractional dispersion models are approximately two to four times larger than reported by Reimus et al. [2003]. Our values are larger because we assume that all of the injected mass is within the extraction well capture zone. Since \( \varphi = 0.01 \) to 0.02 and \( D_m = 1.0 \times 10^{-6} \) to \( 1.7 \times 10^{-6} \text{ m}^2 / \text{day} \) are measured and fixed values, our estimate of the fracture aperture is approximately two to four times smaller than Reimus et al.’s [2003] reported range of 0.6 to 13 mm.

6. Discussion

This paper develops a fractional radial flow equation, and applies the equation to model breakthrough curves from a forced-gradient tracer test in fractured granite [Reimus et al., 2003]. The model uses a fractional partial differential equation with spatially variable coefficients. Numerical solutions are obtained using a novel implicit Euler method to handle the fractional space derivative, and a standard subordination to take care of the fractional time derivative. The space-fractional derivative models anomalous superdispersion, which causes tracer to arrive earlier than the classical Fickian model predicts. Bromide arrival at the pumping well is modeled by a spatially fractional derivative of order \( \alpha = 1.95 \), indicating weak superdispersion that can be attributed to mild heterogeneity of velocities in the fracture(s) [Schumer et al., 2001]. While close to the classical...
\( \alpha = 2 \) space derivative, this fractional derivative term is still important for capturing the very early arrivals (Fig. 4a). A model of the entire BTC required a model of retention, which we chose to be diffusion into large (effectively infinite) matrix blocks. This type of retention can be modeled by a fractional time derivative of order \( \gamma = 1/2 \), and would not only retard, but counteract the super-diffusive growth rate of a plume travelling under natural gradient conditions [Schumer et al., 2003; Dentz and Berkowitz, 2003].

Bromide is a naturally-occurring element that imparts noise and poor detection limits to early, low concentration data. In an attempt to verify that anomalous superdispersion is really taking place, we also examined the breakthrough curve for another nonreactive tracer. This non-naturally occurring tracer (PFBA) also shows evidence of non-Fickian early arrivals, but poor detection at low concentrations makes this evidence inconclusive. In the study of toxic solutes, it is most important to have reliable models of the leading edge of the breakthrough curve. The scatter in the bromide and PFBA data suggests that better tracers are needed: ones that are not found in nature, do not interact significantly with the aquifer solids, and are detectable at extremely low concentrations. For example, the detection of minute amounts of designer-DNA tracer in the Morepen test [Sabir et al., 1999] show that the extreme edges of a plume grow much faster than those outlined by mg/l or \( \mu g/l \) levels of traditional tracers like bromide, and indicates that new tracers are needed to test new models.

Analyses of tests in fractured rock by Becker and Shapiro [2003] and McKenna et al. [2001] do not indicate the anomalously early breakthrough of extremely low concentrations. Thus the early arrivals may not be a ubiquitous occurrence in fractured rock, or simply may be difficult to detect using standard techniques. The data in the present case show only weak heterogeneity, suggesting that short-range transport in fractured rock may be nearer to Fickian behavior than in strongly heterogeneous granular material. On the other hand, a heavy late-time tail on a breakthrough curve is very commonly observed in tracer tests, so the applicability of the more general mobile/immobile, CTRW, or time-fractional models (4) is well-established. Fractally distributed travel velocities and/or retention times imply using a flow equation that accommodates fractional derivatives in both space and time, in order to allow for the possibility of superdisperion (modeled by a fractional space derivative) as well as retardation, subdiffusion, and loss of mobile mass (modeled by a fractional time derivative).

### Appendix A: Numerical Methods

We discuss the basic theory for numerical solution of the fractional advection–dispersion equation (3) on a finite domain \( \mathcal{R}_0 < r < \mathcal{R}_t \) with the initial condition \( c(r,t=0) = F(r) \) for \( \mathcal{R}_0 \leq r \leq \mathcal{R}_t \), and the boundary conditions \( c(r = \mathcal{R}_0,t) = 0 \) and \( \partial c(r = \mathcal{R}_t,t)/\partial r = 0 \) for all \( t \geq 0 \). Numerical methods for the spatially fractional advection–dispersion equation contain some surprises. The implicit (Euler) methods are the preferred approach to discretize the classical PDEs due to their unconditional stability which does not constrain the size of the time step. But, for the fractional ADE with the standard Grünwald estimates, the implicit Euler method (or the Crank–Nicholson method) is unconditionally unstable, while the explicit Euler method can be stable, albeit under a severe stepsize restriction. The situation can be remedied by the use of a shifted Grünwald formula which allows the implicit Euler method (and also the Crank–Nicholson method) to be unconditionally stable. For the shifted Grünwald formula the function evaluations are shifted to the right. The shifted Grünwald formula produces an unconditionally stable finite difference method which is \( O(h) \) consistent. For proof of these remarks refer to Meershaert and Tadjeran [2003].

A Riemann-Liouville fractional derivative on the finite interval \( \mathcal{R}_0 \leq r \leq \mathcal{R}_t \) may be defined (in the sense of generalized functions such as \( \delta(r) \)) as a convolution with a power law [Oldham and Spanier, 1974; Samko et al., 1993]:

\[
\frac{\partial^\alpha c(r,t)}{\partial r^\alpha} = \frac{1}{\Gamma(-\alpha)} \int_0^{r-h} y^{-\alpha} c(r-y,t) dy.
\]

This is equivalent to Grünwald’s infinite sum

\[
\frac{\partial^\alpha c(r,t)}{\partial r^\alpha} = \frac{1}{\Gamma(-\alpha)} \lim_{M \to \infty} \left( \frac{1}{h^\alpha} \sum_{k=0}^M \frac{\Gamma(k-\alpha)}{\Gamma(k+1)} c(r-kh,t), \right)
\]

(A1)

where \( \Gamma(\cdot) \) is the gamma function. This leads to an approximation of the Riemann-Liouville fractional derivative by using a finite number \( M \) of terms, so that \( h = (\mathcal{R}_t - \mathcal{R}_0)/M \) [Miller and Ross, 1993; Podlubny, 1999; Samko et al., 1993].

Note that the value of the fractional derivative at a point \( r \) depends on the function values at that point and all the points at larger radii out to the outer boundary \( \mathcal{R}_0 \). If we define the “normalized” Grünwald weights by

\[
g_k = \frac{\Gamma(k-\alpha)}{\Gamma(-\alpha)} \frac{1}{\Gamma(k+1)}
\]

(A2)

Then the above Grünwald formula may be written:

\[
\frac{\partial^\alpha c(r,t)}{\partial r^\alpha} \approx \frac{1}{h^\alpha} \sum_{k=0}^M g_k c(r-kh,t).
\]

(A3)

Also note that these normalized weights only depend on the order \( \alpha \) and the index \( k \). The first four terms of this sequence are given by \( g_0 = 1, g_1 = -\alpha, g_2 = (\alpha - 1)/2! \), \( g_3 = -\alpha (\alpha - 1)/2! \). Given a numerical approximation scheme, we define \( t_n = n\Delta t \) to be the integration time \( 0 \leq t_n \leq T \), \( \Delta t = h > 0 \) is the grid size in space, \( K = (R_t - R_0)/h \), \( r_i = \mathcal{R}_0 + ih \) for \( i = 0, \ldots, K \) so that \( \mathcal{R}_0 \leq r_i \leq \mathcal{R}_t \), and \( c_i^0 \) is the numerical approximation to \( c(r_i,t_0) \). Similarly \( d_i = d(r_i), \). It can be shown that the implicit Euler (or Crank-Nicholson) approach using the standard Grünwald formula results in an unconditionally unstable method [Meershaert and Tadjeran, 2003]. To obtain a stable (and a convergent) finite difference method, we define and use a shifted Grünwald formulation. The shifted Grünwald formula takes the following form:

\[
\frac{\partial^\alpha c(r,t_n)}{\partial r^\alpha} = \lim_{M \to \infty} \left( \frac{1}{h^\alpha} \sum_{k=0}^M g_k c(r-\mathcal{R}_0-kh,t_n), \right)
\]

from which an approximating formula for the fractional term can be defined by

\[
\frac{\partial^\alpha c(r_i,t_n)}{\partial r^\alpha} \approx \frac{1}{h^\alpha} \sum_{k=0}^i g_k c_{i-k+1}^0 - \frac{2}{h^2} \sum_{k=0}^i g_k c_{i-k-1}^0.
\]

(A5)

Note that for \( \alpha = 2 \), which corresponds to the classical second derivative case, (A5) is just the standard centered difference formula for approximating the second derivative \( (g_0 = 1, g_1 = -2, g_2 = 1, g_3 = g_4 = \cdots = 0) \).
When the shifted Grünwald estimate (A5) is substituted in the implicit Euler method, the resulting difference equations are

$$\frac{c_{i}^{n+1} - c_{i}^{n}}{\Delta t} = -v_{i} \frac{c_{i}^{n+1} - c_{i}^{n+1}}{h} + \frac{d_{i}}{h} \sum_{k=0}^{1} g_{k} c_{i-k+1}^{n+1} + f_{i}^{n+1}$$

(A7)

These equations, together with the boundary conditions (c_{0}^{n+1} = 0, c_{M}^{n+1} = c_{M-1}), result in a linear system of equations whose coefficient matrix is the sum of a lower triangular and a super-diagonal matrices. Defining E_{i} = v_{i} \Delta t/h, and B_{i} = d_{i} \Delta t/h^{2}, then the system defined by (A7) can be re-written:

$$c_{i+1}^{n+1} - c_{i}^{n+1} = -E_{i}(c_{i}^{n+1} - c_{i-1}^{n+1}) + B_{i} \sum_{k=0}^{1} g_{k} c_{i-k+1}^{n+1} + \Delta t f_{i}^{n+1}$$

The above equation can be re-arranged for the like terms to yield

$$-g_{0}B_{i} c_{i+1}^{n+1} + (1 + E_{i} - g_{1} B_{i}) c_{i}^{n+1} - (E_{i} + g_{2} B_{i}) c_{i-1}^{n+1}$$

$$-B_{i} \sum_{k=0}^{1} g_{k} c_{i-k+1}^{n+1} = c_{i}^{n+1} + \Delta t f_{i}^{n+1}.$$  

This difference equation defines a linear system of equations

$$A C^{n+1} = C^{n} + \Delta t F^{n+1}$$

where

$$C^{n+1} = [c_{0}^{n+1}, c_{1}^{n+1}, c_{2}^{n+1}, \ldots, c_{K}^{n+1}]^{T}$$

$$\frac{C^{n+1}}{C^{n}} + \Delta t F^{n+1} = [0, c_{1}^{n}, c_{2}^{n} + \Delta t f_{1}^{n}, c_{3}^{n} + \Delta t f_{2}^{n}, \ldots, c_{K}^{n+1} - \Delta t f_{K-1}^{n}, 0]^{T},$$

and $A = [A_{i,j}]$ is the matrix of coefficients. These coefficients, for $i = 1, \ldots, K-1$ and $j = 1, \ldots, K-1$ are defined as follows (note that $g_{0} = 1$, $g_{1} = -\alpha$):

$$A_{i,j} = \begin{cases} 0, & \text{when } j \geq i + 2 \smallskip 
-g_{0}B_{i}, & \text{when } j = i + 1 \smallskip 
1 + E_{i} - g_{1} B_{i}, & \text{when } j = i \smallskip 
-E_{i} - g_{2} B_{i}, & \text{when } j = i - 1 \smallskip 
-g_{0} - g_{1} B_{i}, & \text{when } j \leq i - 1 \end{cases}$$

while $A_{0,0} = 1$, $A_{0,j} = 0$ for $j = 1, \ldots, K$, $A_{K,K} = 1$, $A_{K,k-1} = -1$, and $A_{K,j} = 0$ for $j = 0, \ldots, K-2$.

The system of equations $A C^{n+1} = C^{n} + \Delta t F^{n+1}$ is solved at time $t_{n}$ to advance the solution to time $t_{n+1}$.

Note that in the present case, the coefficients are independent of time, so the linear system needs to be solved only once, and the matrix multipliers saved to efficiently solve the resulting system of equations as the solution is marched forward in time. A similar approach applies to a more general boundary condition of the third kind of the form $c(R, t) + \rho c(R, t)/\partial R = \delta(t)$.

The Crank–Nicholson discretization, using the shifted Grünwald estimates for the fractional derivative, can also be shown to be unconditionally stable. The general preference for the Crank–Nicholson for the classical PDEs is that it provides a stable finite difference method that is second order accurate $O((\Delta t)^{2}) + O(h^{2})$. However, the Grünwald estimates (standard or shifted) are only $O(h)$ accurate, and therefore in the fractional advection–dispersion differential equations the second order accuracy in time and space is not achieved by the use of the corresponding finite differences.

Acknowledgments. This work was supported by NSF grants DMS-0139927, DMS-0139943, DMS-0417972, EAR-9804848, EAR-9804889, and US DOE grant DE-FG03-98ER14885. We thank anonymous reviewers and the associate editor for excellent comments.

References


