Multivariate Extremes of Generalized Skew-normal Distributions \star

Natalia Lysenko^{a,*}, Parthanil Roy^b, Rolf Waeber^{a,1}

^aETH Zurich, Department of Mathematics, 8092 Zurich, Switzerland ^bETH Zurich, Department of Mathematics, 8092 Zurich, Switzerland and Department of Statistics and Probability, Michigan State University, East Lansing, MI 48824, USA

Abstract

We explore extremal properties of a family of skewed distributions extended from the multivariate normal distribution by introducing a skewing function π . We give sufficient conditions on the skewing function for the pairwise asymptotic independence to hold. We apply our results to a special case of the bivariate skew-normal distribution and finally support our conclusions by a simulation study which indicates that the rate of convergence is quite slow.

Key words: Extreme values, multivariate extremes, domain of attraction, asymptotic independence, generalized skew-normal, skewing function

1 Introduction

Understanding stochastic properties of multivariate extremes is essential in many applied fields. Applications of extreme value theory in the insurance and banking sectors are discussed, for instance, in Embrechts et al. (1997), McNeil et al. (2005), Balkema and Embrechts (2007). The Gaussian distribution lies at the heart of many models in finance and insurance. However, real data on insurance losses and financial returns often indicate departures from

* Corresponding author

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Email address: natalia.lysenko@math.ethz.ch (Natalia Lysenko).

¹ Present address: School of Operations Research and Information Engineering, Cornell University, Ithaca, NY 14853, USA

normality such as the presence of skewness (see, e.g., Lane (2000)), which makes mathematical convenience gained by assuming normality unjustified.

Although multivariate extremes have been studied in detail for many standard distributions, it is in general not known what happens if we relax one or more of the 'nice' properties of such distributions. The goal of this paper is to explore the extremal behavior of the multivariate generalized skew-normal distributions (see Section 2 and also Genton (2004) for a more detailed discussion) obtained from the multivariate normal distribution by relaxing the property of elliptical symmetry using a so-called skewing function. An important role played by skewed distributions in many fields including finance and insurance, biology, meteorology, astronomy, etc. (cf. Hill and Dixon (1982), Azzalini and Capitanio (1999), Genton (2004)) motivates our interest in extremal properties of this class of distributions.

The paper is organized as follows. In Section 2 we give the definition of the multivariate generalized skew-normal distributions and review the results of Chang and Genton (2007) on the extremal behavior of such distributions in the univariate case. In Section 3 we state sufficient conditions for asymptotic independence in the multivariate set-up along with some examples. Finally, in Section 4, we investigate the rate of convergence to the extreme value distribution for both univariate and multivariate skew-normal distributions using simulations. Throughout the paper, we use the following common abbreviations: cdf for cumulative distribution function, pdf for probability density function, *i.i.d.* for independent and identically distributed.

2 Preliminaries

In this section we define the class of generalized skew-normal distributions and review its extremal properties in the univariate case.

Definition 2.1 A *d*-dimensional random vector $\mathbf{X} = (X_1, \ldots, X_d)^T$ follows a generalized skew-normal (GSN) distribution with location parameter $\boldsymbol{\xi}$, scale parameter $\Omega = (\omega_{ij})$ and skewing function π , denoted by $\mathbf{X} \sim GSN_d(\boldsymbol{\xi}, \Omega, \pi)$, if its density function is given by

$$g(\mathbf{x}) = 2\phi_d(\mathbf{x}; \boldsymbol{\xi}, \Omega)\pi(\mathbf{x} - \boldsymbol{\xi}),$$

where $\pi : \mathbb{R}^d \to [0, 1]$ satisfies $\pi(-\mathbf{x}) = 1 - \pi(\mathbf{x})$ and $\phi_d(\mathbf{x}; \boldsymbol{\xi}, \Omega)$ is the pdf of a *d*-dimensional normal random vector with mean vector $\boldsymbol{\xi}$ and covariance matrix Ω .

It is not difficult to check that g is a valid pdf for any skewing function π . One of the nice properties of this class of distributions is that the marginals also

belong to the same class; see Proposition 2.3. The following example gives an important special case.

Example 2.2 (Multivariate flexible skew-normal distribution) If $\pi(\mathbf{x}) = H(P_K(\mathbf{x}))$, where H is any cdf of a continuous random variable symmetric around 0 and P_K is an odd polynomial of order K defined on \mathbb{R}^d , then \mathbf{X} is said to follow a *flexible skew-normal distribution*, which has the density of the form $g(\mathbf{x}) = 2\phi_d(\mathbf{x}; \boldsymbol{\xi}, \Omega)H(P_K(\mathbf{x}))$; see Fig. 1 for an example. This class of distributions, introduced by Ma and Genton (2004), can systematically model light tails, multimodality and skewness. If we take K = 1, $H = \Phi$ (the stan-



Fig. 1. The density and contours of a bivariate flexible skew-normal distribution with $\boldsymbol{\xi} = \mathbf{0}, \ \Omega = I_2, \ H = \Phi, \ K = 3, \ \text{and} \ P_K(x, y) = x + y - 4x^2y - 2xy^2 + 2x^3 - y^3$.

dard normal cdf) and $P_K(\mathbf{x}) = \boldsymbol{\alpha}^T \mathbf{x}$ for some $\boldsymbol{\alpha} \in \mathbb{R}^d$ so that the density has a form $g(\mathbf{x}) = 2\phi_d(\mathbf{x}; \boldsymbol{\xi}, \Omega) \Phi(\boldsymbol{\alpha}^T \mathbf{x})$ then this special case is referred to as *multivariate skew-normal distribution* with location parameter $\boldsymbol{\xi}$, scale parameter Ω and shape parameter $\boldsymbol{\alpha}$ (denoted as $\mathbf{X} \sim SN_d(\boldsymbol{\xi}, \Omega, \boldsymbol{\alpha})$). This distribution, introduced by Azzalini and Dalla Valle (1996), has the advantage that it is still mathematically tractable as well as able to model various unimodal but non-elliptical situations. Clearly, for $\boldsymbol{\alpha} = \mathbf{0}$ it is simply the *d*-dimensional normal distribution, $N_d(\boldsymbol{\xi}, \Omega)$.

The following proposition shows that the marginals of the GSN distributions are also GSN.

Proposition 2.3 Suppose $\mathbf{X} \sim GSN_d(\boldsymbol{\xi}, \Omega, \pi)$ and \mathbf{X} is partitioned as $\mathbf{X}^T =$

 $(\mathbf{X}_{(1)}^T, \mathbf{X}_{(2)}^T)$ of dimensions h and d - h, respectively; denote by

$$\Omega = \begin{pmatrix} \Omega_{11} & \Omega_{12} \\ \Omega_{21} & \Omega_{22} \end{pmatrix} \text{ and } \boldsymbol{\xi} = \begin{pmatrix} \boldsymbol{\xi}_1 \\ \boldsymbol{\xi}_2 \end{pmatrix}$$

the corresponding partitions of Ω and $\boldsymbol{\xi}$, respectively. Then the marginal distribution of $\mathbf{X}_{(1)}$ is $GSN_h(\boldsymbol{\xi}_1, \Omega_{11}, \pi^{(1)})$ with $\pi^{(1)}(\boldsymbol{y}) = E(\pi(\boldsymbol{Z} - \boldsymbol{\xi})|\boldsymbol{Z}^{(1)} = \boldsymbol{y})$, where $\boldsymbol{Z} \sim N_d(\boldsymbol{\xi}, \Omega)$ and $\boldsymbol{Z} = (\boldsymbol{Z}^{(1)}, \boldsymbol{Z}^{(2)})$ is the corresponding partition of \boldsymbol{Z} .

Proof Since $\mathbf{X} \sim GSN_d(\boldsymbol{\xi}, \Omega, \pi)$, it has density $g(\mathbf{x}) = 2\phi_d(\mathbf{x}; \boldsymbol{\xi}, \Omega)\pi(\mathbf{x} - \boldsymbol{\xi})$ with notations in Definition 2.1. Let $\mathbf{x}^T = (\mathbf{y}^T, \mathbf{z}^T)$ be the corresponding partition of the variable \mathbf{x} . Then the density of $\mathbf{X}^{(1)}$ is given by (with the vectors of variables written as row vectors instead of column vectors)

$$h(\mathbf{y}^{T}) = \int_{\mathbb{R}^{d-h}} g(\mathbf{y}^{T}, \mathbf{z}^{T}) d\mathbf{z}$$

= $2 \int_{\mathbb{R}^{d-h}} \phi_{d}(\mathbf{y}^{T}, \mathbf{z}^{T}; \boldsymbol{\xi}, \Omega) \pi \left((\mathbf{y} - \boldsymbol{\xi}^{(1)})^{T}, (\mathbf{z} - \boldsymbol{\xi}^{(2)})^{T} \right) d\mathbf{z}$
= $2 \phi_{h}(\mathbf{y}^{T}; \boldsymbol{\xi}^{(1)}, \Omega_{11}) \int_{\mathbb{R}^{d-h}} \pi \left((\mathbf{y} - \boldsymbol{\xi}^{(1)})^{T}, (\mathbf{z} - \boldsymbol{\xi}^{(2)})^{T} \right) \psi(\mathbf{z}^{T}) d\mathbf{z}$

where ψ is the density of $Z^{(2)}$ given $Z^{(1)} = y$. This proves the result.

We now turn our attention to the extremal behavior of these distributions in the univariate case. Without loss of generality it can be assumed that the location parameter is 0 and the scale parameter is 1. We use the notation $X \sim GSN(\pi)$ and $X \sim SN(\alpha)$ to mean $X \sim GSN_1(0, 1, \pi)$ and $X \sim$ $SN_1(0, 1, \alpha)$, respectively. The following result summarizes the implications of Propositions 2.1 and 2.2 in Chang and Genton (2007) for univariate generalized skew-normal distributions. For the underlying extreme value theory, see, for example, Resnick (1987), Embrechts et al. (1997), de Haan and Ferreira (2006).

Proposition 2.4 (Chang and Genton (2007)) Let F be the cdf of a random variable $X \sim GSN(\pi)$. Assume that the skewing function $\pi : \mathbb{R} \to [0, 1]$ and the cdf F satisfy the following conditions:

- i) π is continuous and there exists a constant M > 0 such that $\pi(x)$ is positive and monotone for x > M;
- *ii*) π has continuous second derivative;
- *iii*) there exists a constant $M^* > 0$ such that F''(x) < 0 for $x > M^*$;

iv) either $\lim_{x\to\infty} \pi(x) = \eta \in (0,1]$ or $\lim_{x\to\infty} \frac{(1-F(x))F''(x)}{(F'(x))^2} = -1.$

Then $F \in MDA(\Lambda)$, where Λ denotes the Gumbel distribution given by $\Lambda(x) = \exp(-e^{-x})$ for $x \in (-\infty, \infty)$.

Here the notation $G \in MDA(\Lambda)$ means G belongs to the maximum domain of attraction of Λ (the Gumbel distribution). Using Proposition 2.4, Chang and Genton (2007) established that the univariate flexible skew-normal distribution with $H = \Phi$ (and hence in particular the univariate skew-normal distribution) belongs to the maximum domain of attraction of the Gumbel distribution.

3 Conditions for Asymptotic Independence

Recall that a *d*-dimensional random vector $\mathbf{X} = (X_1, \dots, X_d)^T$ with cdf F is said to be *asymptotically independent* if F is in the (componentwise) maximum domain of attraction of a distribution G with independent components (i.e., $G(\mathbf{x}) = \prod_{i=1}^{d} G_i(x_i)$ where G_i is the *i*th marginal of G). Since the density g in Definition 2.1 is strongly connected to the multivariate normal density and any multivariate normal random vector with pairwise correlations less than 1 is asymptotically independent (see Sibuya (1960)), we expect the asymptotic independence to hold also for a generalized skew-normal vector as long as the skewing function π satisfies some mild conditions. As asymptotic independence is essentially a pairwise concept (see Remark 6.2.5 in de Haan and Ferreira (2006)), in the next two results we give *sufficient* conditions for pairwise asymptotic independence of a generalized skew-normal random vector \mathbf{X} in terms of the skewing functions of the univariate and bivariate marginals, which can be calculated from the skewing function π using Proposition 2.3.

Theorem 3.1 Consider $\mathbf{X} \sim GSN_d(\boldsymbol{\xi}, \Omega, \pi)$. Fix $i, j \in \{1, 2, \dots, d\}$ with $i \neq j$ j and $\frac{\omega_{ij}}{\sqrt{\omega_{ii}\omega_{jj}}} < 1$. Let $\pi_i, \pi_j : \mathbb{R} \to [0,1]$ be the skewing functions of X_i and X_j , respectively. Assume that the skewing functions satisfy the following conditions:

- i) there exists a constant $M_1 \in \mathbb{R}$ such that either $\pi_i(x) \leq \pi_i(x)$ or $\pi_i(x) \leq \pi_i(x)$ $\begin{array}{l} \stackrel{'}{\pi_i(x) \text{ for all } x \geq M_1;}\\ ii) \ \liminf_{u \to \infty} \pi_i(u) > 0, \ \liminf_{u \to \infty} \pi_j(u) > 0. \end{array}$

Then X_i and X_j are asymptotically independent.

Proof To prove this theorem we assume without loss of generality that $\xi_k = 0$ and $\omega_{kk} = 1$ for all $k = 1, \ldots, d$. Furthermore, for simplicity of notation, we only consider the case i = 1, j = 2, and $\pi_1(x) \leq \pi_2(x)$ for x larger than some constant M_1 . Define $\omega := \omega_{12} < 1$. By Theorem 6.2.3 in de Haan and Ferreira (2006), in order to establish asymptotic independence of X_1 and X_2 we need to show that

$$\lim_{t \to \infty} \frac{P(X_1 > U_1(t), X_2 > U_2(t))}{P(X_1 > U_1(t))} = 0,$$
(3.1)

where $U_i(t) := \inf\{x \in \mathbb{R} : F_i(x) \ge 1 - 1/t\}$, for i = 1, 2. Since we assumed that $\pi_1(x) \leq \pi_2(x)$ for large x, it follows that $U_1(t) \leq U_2(t)$ for large t. Note that by condition *ii*) $\pi_1(u) > 0$ for large u and therefore $U_1(t) \to \infty$ as $t \to \infty$. So the limit in (3.1) can be bounded above as follows

$$\lim_{t \to \infty} \frac{P(X_1 > U_1(t), X_2 > U_2(t))}{P(X_1 > U_1(t))} \le \lim_{t \to \infty} \frac{P(X_1 > U_1(t), X_2 > U_1(t))}{P(X_1 > U_1(t))} = \lim_{u \to \infty} \frac{P(X_1 > u, X_2 > u)}{P(X_1 > u)}.$$
(3.2)

Hence, it is enough to show that the limit in (3.2) is equal to zero. From condition ii), there exist constants $M_2, c_0 > 0$ such that $\pi_1(u) > c_0$ for all $u > M_2$. Hence, for all $u > M_2$, the denominator in (3.2) can be bounded below by

$$P(X_1 > u) = \int_u^\infty 2\phi(x)\pi_1(x)dx \ge 2c_0 \int_u^\infty \phi(x)dx$$

and the numerator of (3.2) can be bounded above by

$$P(X_1 > u, X_2 > u) = \int_u^\infty \int_u^\infty 2\phi_2(x, y; \omega) \pi_{12}(x, y) dx dy$$
$$\leq 2 \int_u^\infty \int_u^\infty \phi_2(x, y; \omega) dx dy,$$

where $\pi_{12} : \mathbb{R}^2 \to [0, 1]$ is the bivariate skewing function of (X_1, X_2) .

Suppose $(Z_1, Z_2) \sim N_2(\mathbf{0}, \Sigma_{\omega})$ with $\Sigma_{\omega} := \begin{pmatrix} 1 & \omega \\ \omega & 1 \end{pmatrix}$. Combining the above

bounds, we get

$$\frac{P(X_1 > u, X_2 > u)}{P(X_1 > u)} \le \frac{\int_u^\infty \int_u^\infty \phi_2(x, y; \omega) dx dy}{c_0 \int_u^\infty \phi(x) dx}$$
$$= \frac{1}{c_0} \frac{P(Z_1 > u, Z_2 > u)}{P(Z_1 > u)} \to 0$$

as $u \to \infty$ by Corollary 5.28 in Resnick (1987). This completes the proof. \Box

The following corollary is an immediate consequence of Proposition 2.4 and Theorem 3.1.

Corollary 3.2 Let F be the cdf of a bivariate generalized skew-normal random vector $\mathbf{X} \sim GSN_2(\boldsymbol{\xi}, \Omega, \pi)$ with $\frac{\omega_{12}}{\sqrt{\omega_{11}\omega_{22}}} < 1$. Assume that the skewing functions π_1 and π_2 satisfy the following conditions:

- i) there exists a constant $M_1 \in \mathbb{R}$ such that either $\pi_1(x) \leq \pi_2(x)$ or $\pi_2(x) \leq \pi_1(x)$ for all $x \geq M_1$;
- *ii*) π_1 and π_2 are continuous and there exists a constant $M_2 > 0$ such that both $\pi_1(x)$ and $\pi_2(x)$ are monotone for $x > M_2$;
- *iii*) π_1 and π_2 have continuous second derivatives;
- *iv*) there exists a constant $M^* > 0$ such that $f'_1(x) < 0$ and $f'_2(x) < 0$ for $x > M^*$, where f_i is the pdf of X_i , i = 1, 2;
- v) $\lim_{x \to \infty} \min \{\pi_1(x), \pi_2(x)\} = \eta \in (0, 1].$

Then $F \in MDA(G)$, where

$$G(x_1, x_2) = \exp(-e^{-x_1} - e^{-x_2}).$$
(3.3)

Condition i) on the skewing function in Theorem 3.1 is often satisfied. Since condition ii) is rather stringent, we relax it slightly by introducing other requirements on the skewing functions in the next result.

Theorem 3.3 Let $\mathbf{X} \sim GSN_d(\boldsymbol{\xi}, \Omega, \pi)$ as in Theorem 3.1. Fix $i, j \in \{1, 2, \ldots, d\}$ with $\frac{\omega_{ij}}{\sqrt{\omega_{ii}\omega_{jj}}} < 1$ and $i \neq j$. Let $\pi_i, \pi_j : \mathbb{R} \to [0, 1]$ be the skewing functions of X_i and X_j respectively, and $\pi_{ij} : \mathbb{R}^2 \to [0, 1]$ be the bivariate skewing function of (X_i, X_j) . Assume that π_i and π_j satisfy condition i) of Theorem 3.1 and additionally

- *ii*) there exists a constant $M_2 \in \mathbb{R}$ such that both $\pi_i(x)$ and $\pi_j(x)$ are monotone for $x > M_2$;
- *iii*) there exists a constant $M_3 \in \mathbb{R}$ such that $\pi_{ij}(x, y)$ is monotone for $x, y > M_3$ in the sense that either $\pi_{ij}(x', y') \leq \pi_{ij}(x, y)$ for all $x' \geq x$ and $y' \geq y$ or $\pi_{ij}(x', y') \geq \pi_{ij}(x, y)$ for all $x' \geq x$ and $y' \geq y$;
- *iv*) there exist constants $b > 1, u_0, C > 0$ such that $\pi_{ij}(u, u) \leq C\pi_i(bu)$ and $\pi_{ij}(u, u) \leq C\pi_j(bu)$ for all $u \geq u_0$.

Then X_i and X_j are asymptotically independent.

Proof As in the proof of Theorem 3.1, we assume $\xi_k = 0$ and $\omega_{kk} = 1$ for all $k = 1, \ldots, d, i = 1, j = 2$, and $\pi_1(x) \leq \pi_2(x)$ for $x > M_1$. Once again it is enough to show that the limit (3.2) is equal to zero. We may also assume that $\lim_{u\to\infty} \pi_1(u) = 0$ since otherwise we can use Theorem 3.1. Due to condition iv, it follows that $\lim_{u\to\infty} \pi_{12}(u, u) = 0$. This, combined with condition iii, implies that both π_1 and π_{12} are eventually decreasing functions. This gives the following upper bound on the numerator of (3.2) for large enough u:

$$P(X_1 > u, X_2 > u) \le 2\pi_{12}(u, u) \int_u^\infty \int_u^\infty \phi_2(x, y; \omega) dx dy$$

= $2\pi_{12}(u, u) P(Z_1 > u, Z_2 > u)$
 $\le 2\pi_{12}(u, u) P(Z_1 + Z_2 > 2u),$

with $(Z_1, Z_2) \sim N_2(\mathbf{0}, \Sigma_{\omega})$ as before. Since π_1 is eventually decreasing, for large u and b > 1, $\pi_1(bu) \leq \pi_1(u)$ and hence the denominator in (3.2) can be bounded below by

$$P(u < X_1 < bu) \ge 2\pi_1(bu) \int_u^{bu} \phi(x) dx = 2\pi_1(bu) P(u < Z_1 \le bu).$$

Using the above bounds along with condition iv), we get

$$\lim_{u \to \infty} \frac{P(X_1 > u, X_2 > u)}{P(X_1 > u)} \le C \lim_{u \to \infty} \frac{P(Z_1 + Z_2 > 2u)}{P(u < Z_1 \le bu)}$$
$$= C \lim_{u \to \infty} \frac{1 - \Phi(au)}{\Phi(bu) - \Phi(u)}$$

where $a := \sqrt{\frac{2}{1+\omega}} > 1$. Applying l'Hôpital's rule, we obtain

$$\lim_{u \to \infty} \frac{P(X_1 > u, X_2 > u)}{P(X_1 > u)} \le C \lim_{u \to \infty} \frac{ae^{-\frac{a^2u^2}{2}}}{e^{-\frac{u^2}{2}} - be^{-\frac{b^2u^2}{2}}} = 0$$

since a, b > 1. This completes the proof.

Example 3.4 (The Bivariate Skew-Normal Case) We now apply Theorem 3.1 and Theorem 3.3 to a bivariate skew-normal random vector. We use the notation $\mathbf{X} = (X_1, X_2)^T \sim SN_2(\alpha_1, \alpha_2; \omega)$ to mean $\mathbf{X} \sim SN_2(\mathbf{0}, \Omega, (\alpha_1, \alpha_2)^T)$ with $\Omega = \begin{pmatrix} 1 & \omega \\ \omega & 1 \end{pmatrix}$. In this case, using Proposition 2 in Azzalini and Capitanio (1999), it follows that $X_i \sim SN_1(0, 1, \bar{\alpha}_i), i = 1, 2$, where

$$\bar{\alpha}_1 = \frac{\alpha_1 + \omega \alpha_2}{\sqrt{1 + (1 - \omega^2)\alpha_2^2}} \quad \text{and} \quad \bar{\alpha}_2 = \frac{\alpha_2 + \omega \alpha_1}{\sqrt{1 + (1 - \omega^2)\alpha_1^2}};$$

i.e., $\pi_i(x) = \Phi(\bar{\alpha}_i x)$, i = 1, 2, and $\pi_{12}(x_1, x_2) = \Phi(\alpha_1 x_1 + \alpha_2 x_2)$. Unfortunately, Theorems 3.1 and 3.3 do not establish asymptotic independence of X_1 and X_2 for all parameters $\alpha_1, \alpha_2 \in \mathbb{R}$ and $\omega \in (-1, 1)$. Table 1 shows the range of parameter values for which asymptotic independence follows directly from these theorems, although we conjecture that it is true for all possible parameter values. By the definition of asymptotic independence it follows that the bivariate skew-normal distribution is in the maximum domain of attraction of (3.3) as long as α_1 and α_2 are as in Table 1. For $\omega \neq 0$ the asymptotic independence follows trivially from Theorems 3.1 and 3.3. If $\omega = 0$ we have $\alpha_1 = \bar{\alpha}_1$ and $\alpha_2 = \bar{\alpha}_2$. Hence, for $\alpha_1, \alpha_2 < 0$ we can use Theorem 3.3. It is then enough to consider the case $\alpha_2 \geq 0$. Taking i.i.d. N(0, 1) random variables Z_1, Z_2 we get, following the proof of Theorem 3.1, that $P(X_1 > U_1(t), X_2 > U_2(t)) \leq 2P(Z_1 > U_1(t))P(Z_2 > U_2(t))$. Also

ω	$lpha_1$	$lpha_2$	
$\omega = 0$	$\alpha_1 \in \mathbb{R}$	$\alpha_2 \in \mathbb{R}$	
$\omega > 0$	$\alpha_1 \ge 0$	$\alpha_2 \ge -\omega\alpha_1$	
	$\alpha_1 \leq 0$	$\alpha_2 \ge -\frac{1}{\omega}\alpha_1$	
	$\alpha_1 < 0$	$\alpha_2 < 0$	
$\omega < 0$	$\alpha_1 \geq 0$	$-\omega\alpha_1 \le \alpha_2 \le -\frac{1}{\omega}\alpha_1$	
	$\alpha_1 < 0$	$\alpha_2 < 0$	

Table 1

Parameters α_1 , α_2 and ω for which asymptotic independence holds for $SN_2(\alpha_1, \alpha_2; \omega)$.

 $P(X_2 > U_2(t)) \ge P(Z_2 > U_2(t))$ since $\alpha_2 \ge 0$. Hence, it follows that the limit in (3.1) is equal to 0 establishing the asymptotic independence in the $\omega = 0$ case.

4 Simulations

The relevance of the results of Section 3 is determined by how many observations one has to have in order to make the asymptotic approximations acceptable. We first look at the rate of marginal convergence and then comment on the asymptotic independence using simulated skew-normal random vectors².

One may expect a rather slow rate of convergence of the normalized maxima for the GSN distribution as is the case for the normal distribution which has a rate of $O(\frac{1}{\log n})$ (cf. Hall (1979)), although computing the rate is still an open problem in the GSN case. Fig. 2a and 2b compare QQ-plots for 1,000 normalized maxima $\tilde{M}_n := (M_n - b_n)/a_n$ with the block sizes $n = 10^3$ and $n = 10^6$, where $M_n := \max_{1 \le i \le n} X_i$, X_i 's are i.i.d. from $SN(\alpha)$ distribution and a_n and b_n are the normalizing constants from the extreme value theory. As can be seen from Fig. 2a, a random sample of size 10^3 from a skew-normal distribution might not be sufficient to justify the use of the extreme value theory results. More convincing QQ-plots in Fig. 2b with $n = 10^6$ confirm the statement of Proposition 2.4.

To explore the rate at which components of the bivariate skew-normal random vectors approach independence, we first produced the so-called *Chi-plots* and *K-plots* to detect dependence in the simulated data; see Fig. 3. For details on

 $^{^2~}$ The simulations were carried out with the statistical package R (2007) using library $\mathtt{sn.}$



Fig. 2. The QQ-plots for \tilde{M}_n , where X follows a skew-normal distribution with $\alpha = -10, -2, 0, 2, 10.$

how to construct these plots and justifications, see Genest and Favre (2007). In the Chi-plot of pairs (λ_i, χ_i) , the values of χ_i away from zero indicate departures from the hypothesis of independence. The horizontal dashed bounds are drawn at the levels $\pm c_p/\sqrt{k}$ with $c_p = 2.18$ so that approximately 99% of the pairs (λ_i, χ_i) lie within these bounds (cf. Genest and Favre (2007)).



Fig. 3. Chi-plots and K-plots for simulated random samples of size 100 for $\mathbf{X} \sim SN_2(\alpha_1, \alpha_2; \omega)$ (a)-(b) and the corresponding coordinatewise maxima \mathbf{M}_n with block sizes $n = 10^3$ (c)-(d) and $n = 10^6$ (e)-(f). The parameter values are $\alpha_1 = 2$, $\alpha_2 = 3$ and $\omega = 0.6$.

$\omega = 0.6$								
	$\alpha_1 = 2, \alpha_2 = 3$		$\alpha_1 = 2, \alpha_2 = -3$		$\alpha_1 = -2, \alpha_2 = 3$			
n	$p_{ ho}$	$p_{ au}$	$p_{ ho}$	$p_{ au}$	$p_{ ho}$	$p_{ au}$		
10^{6}	1	1	0.78	0.78	0.98	0.98		
10^{4}	0.97	0.96	0.54	0.55	0.98	0.98		
10^{3}	0.97	0.97	0.18	0.18	0.89	0.89		
10^{2}	0.87	0.86	0.18	0.18	0.50	0.48		
$\omega = 0.1$								
10^{6}	1	0.99	1	0.99	0.99	0.99		
10^{4}	1	1	1	1	0.99	0.99		
10^{3}	1	1	0.96	0.97	0.99	0.99		
10^{2}	1	1	0.79	0.76	0.99	0.99		
$\omega = 0$								
10^{6}	0.99	0.98	1	1	1	1		
10^{4}	1	1	1	1	0.98	0.98		
10^{3}	0.99	0.99	1	1	0.99	0.99		
10^{2}	0.99	0.98	1	1	0.99	0.99		
$\omega = -0.1$								
10^{6}	1	1	0.98	0.98	1	1		
10^{4}	1	1	0.96	0.96	0.97	0.98		
10^{3}	0.99	1	0.99	0.99	0.98	0.98		
10^{2}	1	1	0.99	0.99	0.99	0.99		
$\omega = -0.6$								
10^{6}	0.98	0.98	1	1	1	1		
10^{4}	1	1	0.97	0.97	1	1		
10^{3}	0.99	0.99	1	1	0.99	0.99		
10^{2}	1	1	1	1	0.99	0.99		

Table 2 $\,$

Proportions of the tests based on Spearman's rho (p_{ρ}) and Kendall's tau (p_{τ}) for which there was not enough evidence to reject the null hypothesis of independence of the coordinatewise maxima at level $\alpha = 1\%$. Simulated data: 100 block maxima \mathbf{M}_n from $SN_2(\alpha_1, \alpha_2; \omega)$ distribution; each test was repeated 100 times.

The 45°-line on the K-plot corresponds to the case of independence, and the superimposed curve corresponds to the case of perfect positive dependence. As can be seen from Fig. 3a and 3b, the components of the $SN_2(2,3;0.6)$ random vector exhibit positive dependence, which eventually disappears for the maxima as the block size n becomes large; see Fig. 3c - 3f.

Using Spearman's rho and Kendall's tau, we test the hypothesis of independence of coordinatewise maxima from an $SN_2(\alpha_1, \alpha_2; \omega)$ distribution. Again the reader is referred to Genest and Favre (2007) and Genest and Verret (2005) for details on rank-based tests of independence. The tests are based on 100 blocks of coordinatewise maxima with block size n, and each test is repeated 100 times. In Table 2 we report proportions of the tests which could not reject the null hypothesis of independence at approximately level $\alpha = 1\%$; p_{ρ} and p_{τ} denote the proportion of the tests based on Spearman's rho and Kendall's tau, respectively, with the P-values exceeding 0.01. The values highlighted in bold correspond to the choice of parameters within the range specified in Table 1 for which we have an analytical proof of asymptotic independence. These results indicate that even relatively small block sizes such as n = 100and n = 1000 are sufficient for the convergence of the maximal components to being independent. The rest of the values support our conjecture that in fact asymptotic independence holds for all possible parameter values. Low proportions of insignificant tests corresponding to $\alpha_1 = 2, \alpha_2 = -3, \omega = 0.6$ might be due to slower rates of convergence. A further analytical investigation of the asymptotic independence property is required.

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